

Safety in Integrated Systems Health Engineering and Management

Nancy G. Leveson

MIT

- You've carefully thought out all the angles.
- You've done it a thousand times.
- It comes naturally to you.
- You know what you're doing, it's what you've been trained to do your whole life.
- Nothing could possibly go wrong, right?

Think Again.



Reliability Engineering vs. System Safety

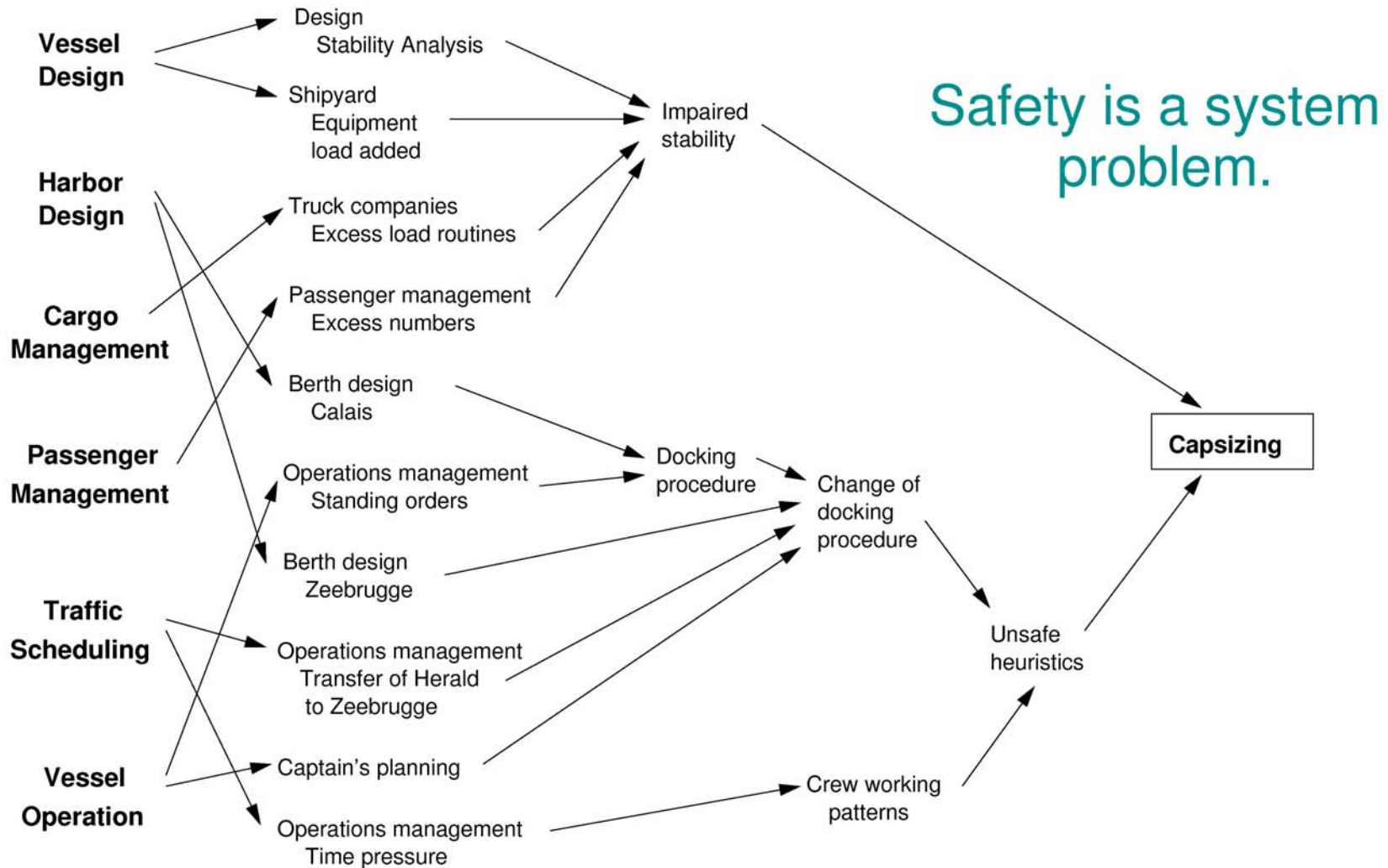
- Both arose after World War II
- Reliability engineering often confused with system safety engineering, but they are different and sometimes even conflict
- Reliability engineering focuses on preventing failure
- System safety focuses on eliminating and controlling hazards
 - Considers interactions among components and not just component failures
 - Includes non-technical aspects of systems
- Highly reliable systems may be unsafe and safe systems may not be reliable.

Traditional Chain-of-Events Accident Causality Models

- Explain accidents in terms of multiple events, sequenced as a forward chain over time.
- Events linked together by direct relationships (ignore indirect, non-linear relationships).
- Events almost always involve component failure, human error, or energy-related events.
- Form the basis for most safety-engineering and reliability engineering analysis (FTA, FMEA, PRA) and design.

Limitations of Event-Chain Causality Models

- Social and organizational factors
- System accidents
- Software Error
- Human Error
 - Cannot effectively model human behavior by decomposing it into individual decisions and actions and studying it in isolation from
 - physical and social context
 - value system in which it takes place
 - dynamic work process
- Adaptation
 - Major accidents involve systematic migration of organizational behavior to higher levels of risk.



New Approaches Based on Systems Theory

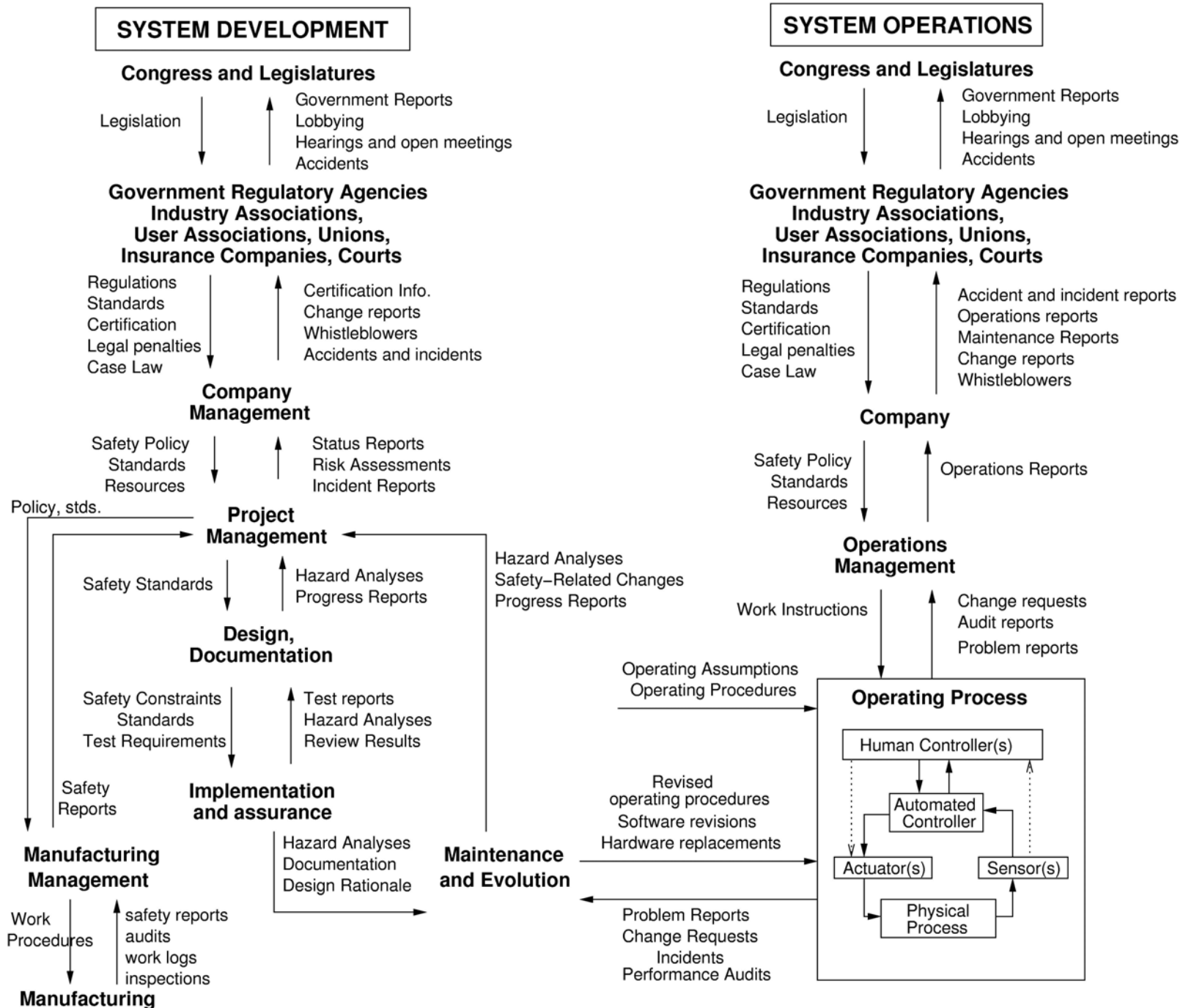
- Rasmussen – Hierarchical model of accident causation
- STAMP (Systems Theoretic Accident Modeling and Processes)
 - New accident causation model based on systems theory
 - New hazard analysis technique (STPA)
 - Works for hardware, software, human error, social factors, management errors, etc.
 - Includes what we do now, but more
 - New, more powerful risk management tools (including policy analysis and evaluation and “canary in the coal mine”)
 - Designing for safety
 - Root cause analysis and incident/accident investigation

A Systems Theory Model of Accidents

- Accidents arise from interactions among humans, machines, and the environment.
 - Not simply chains of events or linear causality, but more complex types of causal connections.
- Safety is an emergent property that arises when components of system interact with each other within a larger environment.
 - A set of constraints related to behavior of components in system enforces that property.
 - Accidents when interactions violate those constraints (a lack of appropriate constraints on the interactions).
 - Software as a controller embodies or enforces those constraints.

A Systems Theory Model of Accidents

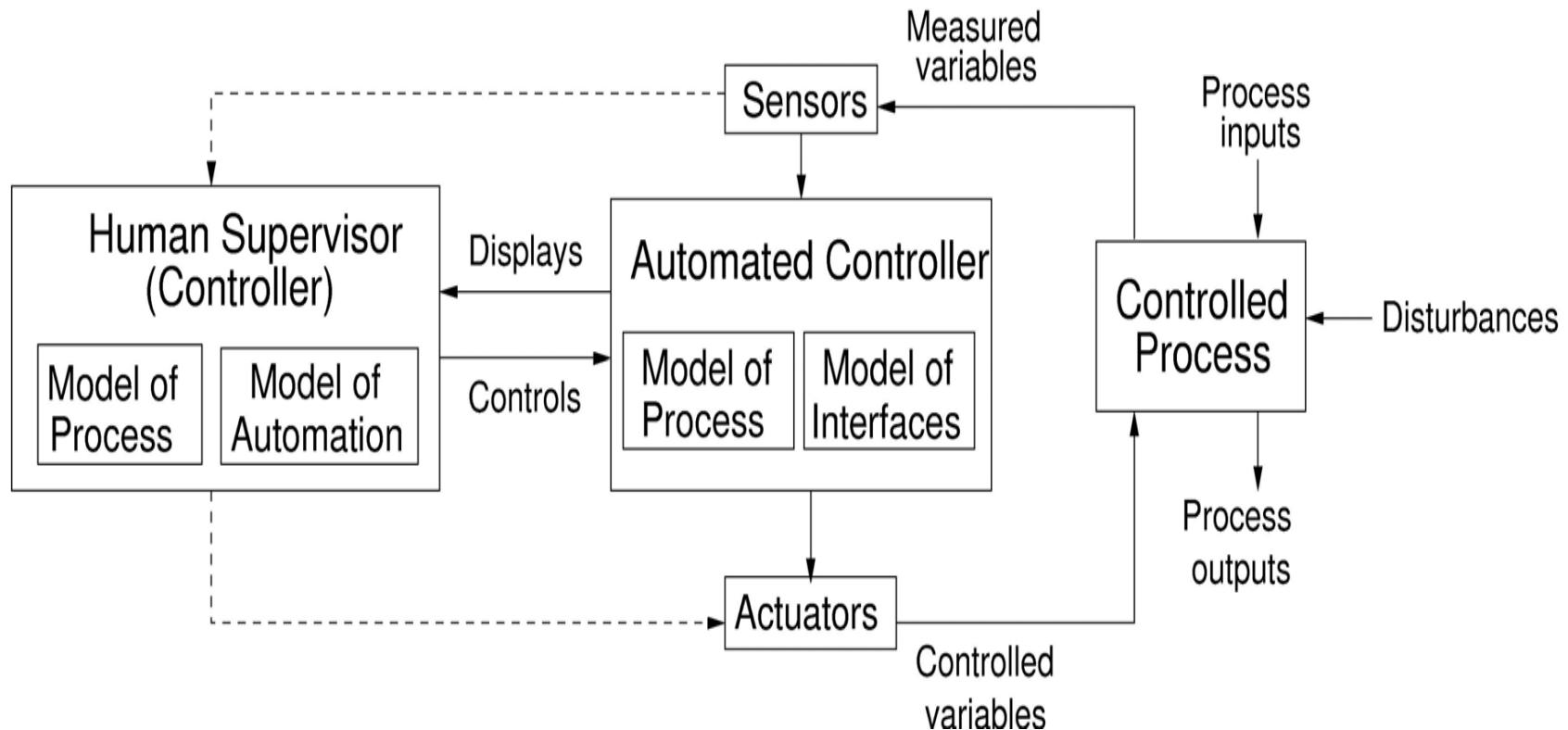
- Systems should not be treated as a static design
 - A socio–technical system is a dynamic process continually adapting to achieve its ends and to react to changes in itself and its environment
 - Preventing accidents requires designing a control structure to enforce constraints on system behavior and adaptation.



A Systems Theory Model of Accidents (3)

- Views accidents as a control problem
 - e.g., O-ring did not control propellant gas release by sealing gap in field joint
 - Software did not adequately control descent speed of Mars Polar Lander.
- Events are the result of the inadequate control
 - Result from lack of enforcement of safety constraints
- To understand accidents, need to examine control structure itself to determine why inadequate to maintain safety constraints and why events occurred.

Not a "blame" model – trying to understand "why"



Process models must contain:

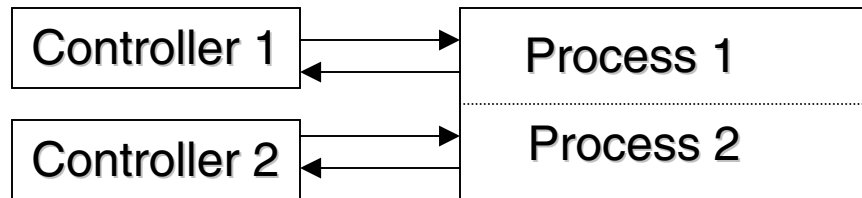
- Required relationship among process variables
- Current state (values of process variables)
- The ways the process can change state

Some Causal Factors in Accidents

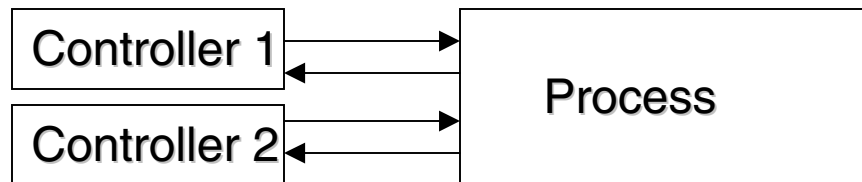
- Design does not enforce safety constraints.
 - mishandled disturbances, failures, dysfunctional interactions
- Controller provides inadequate control actions
 - inconsistent/incorrect process models
 - inadequate or missing feedback
 - inadequate control algorithms
 - time lags

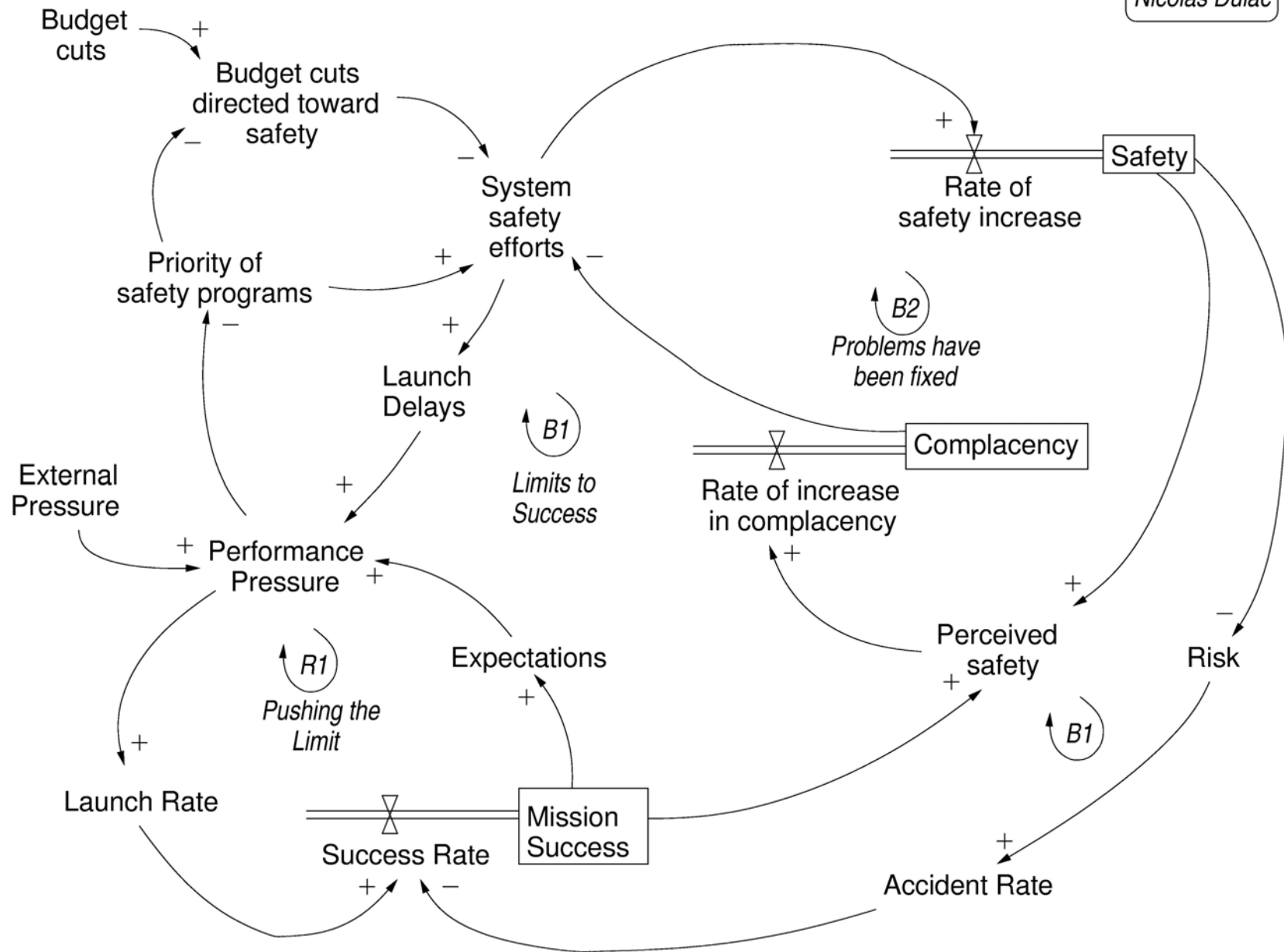
Some Causal Factors in Accidents (2)

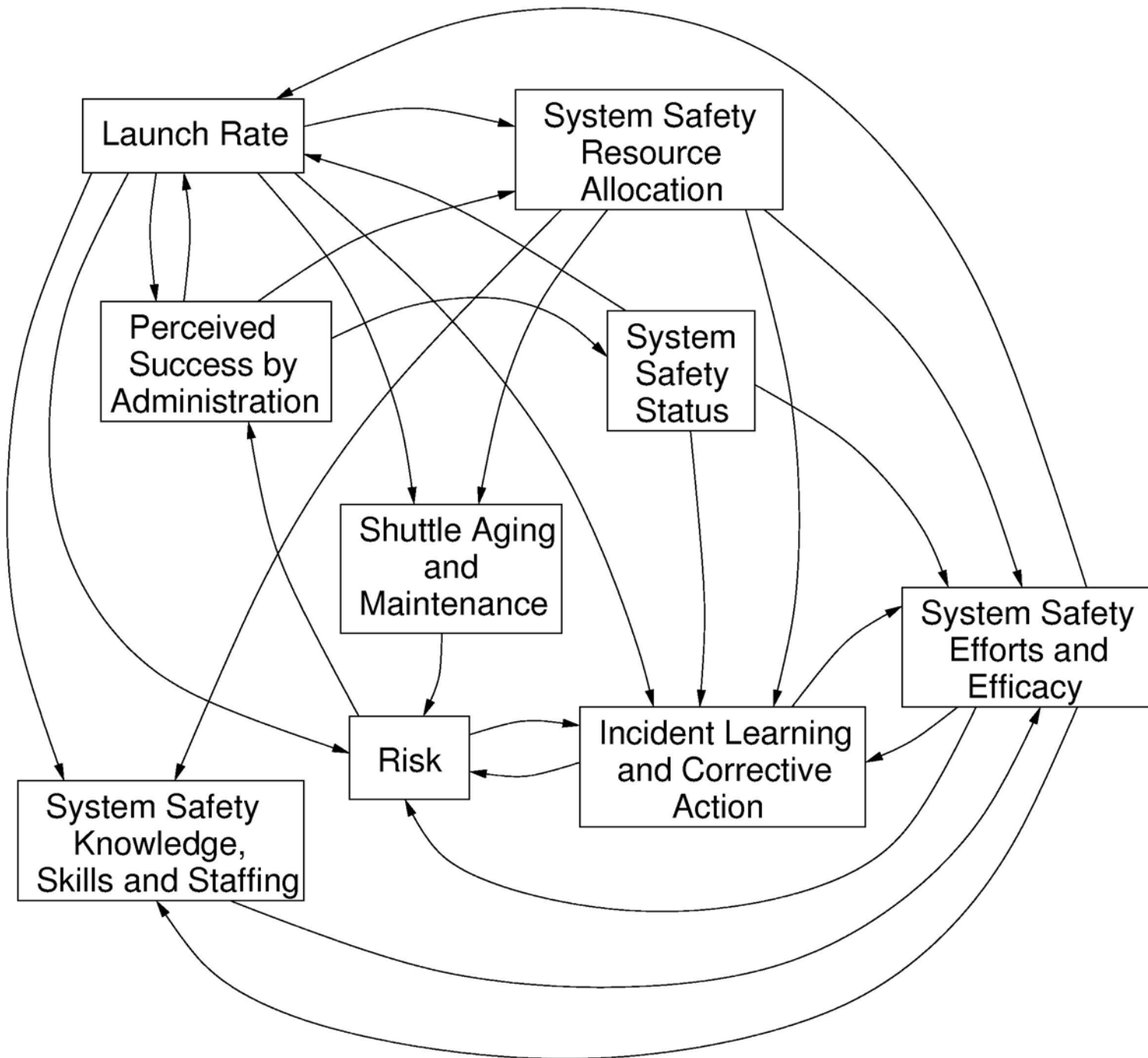
- Control structure degrades over time, asynchronous evolution.
- Control actions inadequately coordinated among multiple controllers.
 - Boundary areas



- Overlap areas (side effects of decisions and control actions)



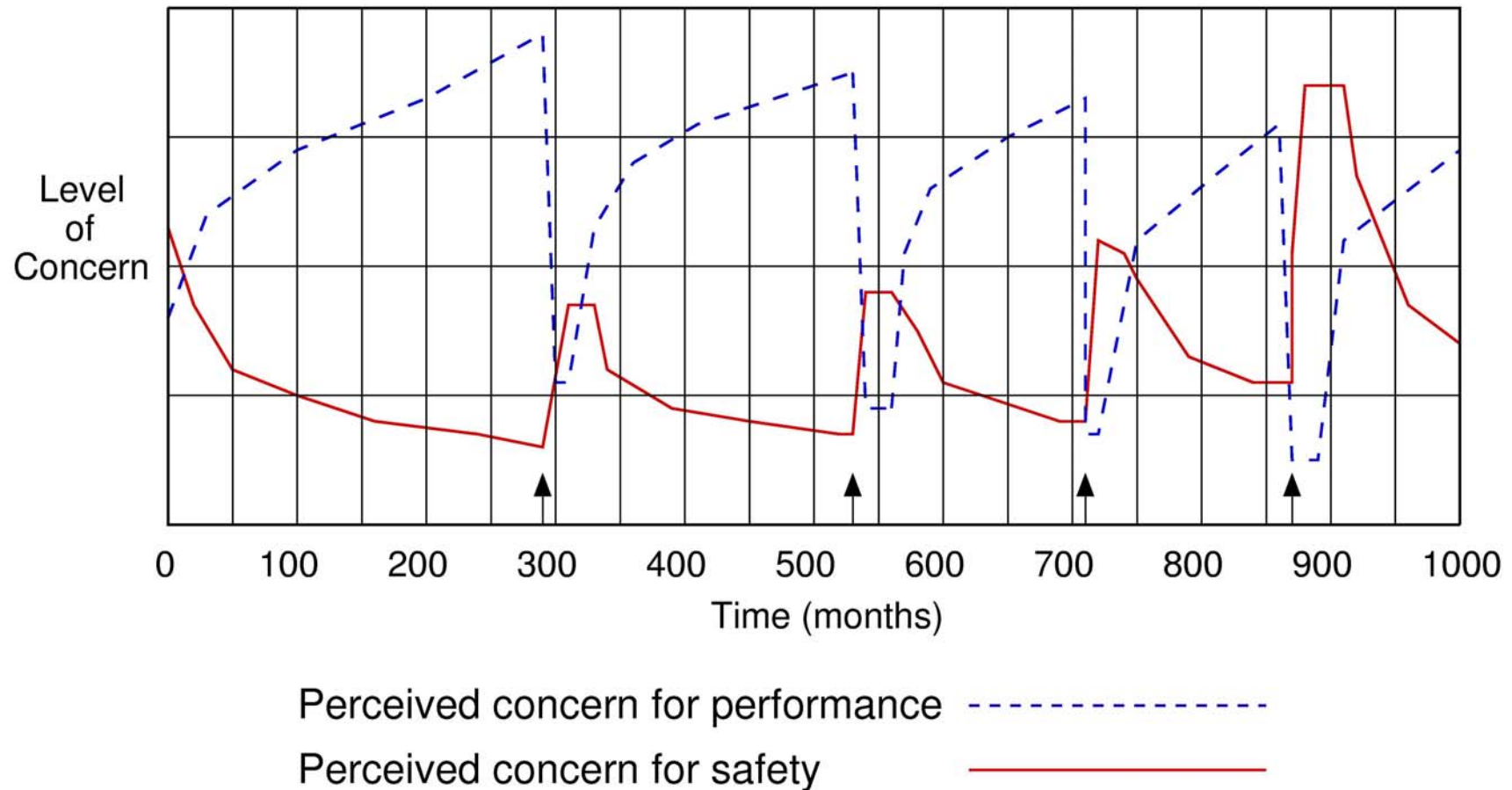




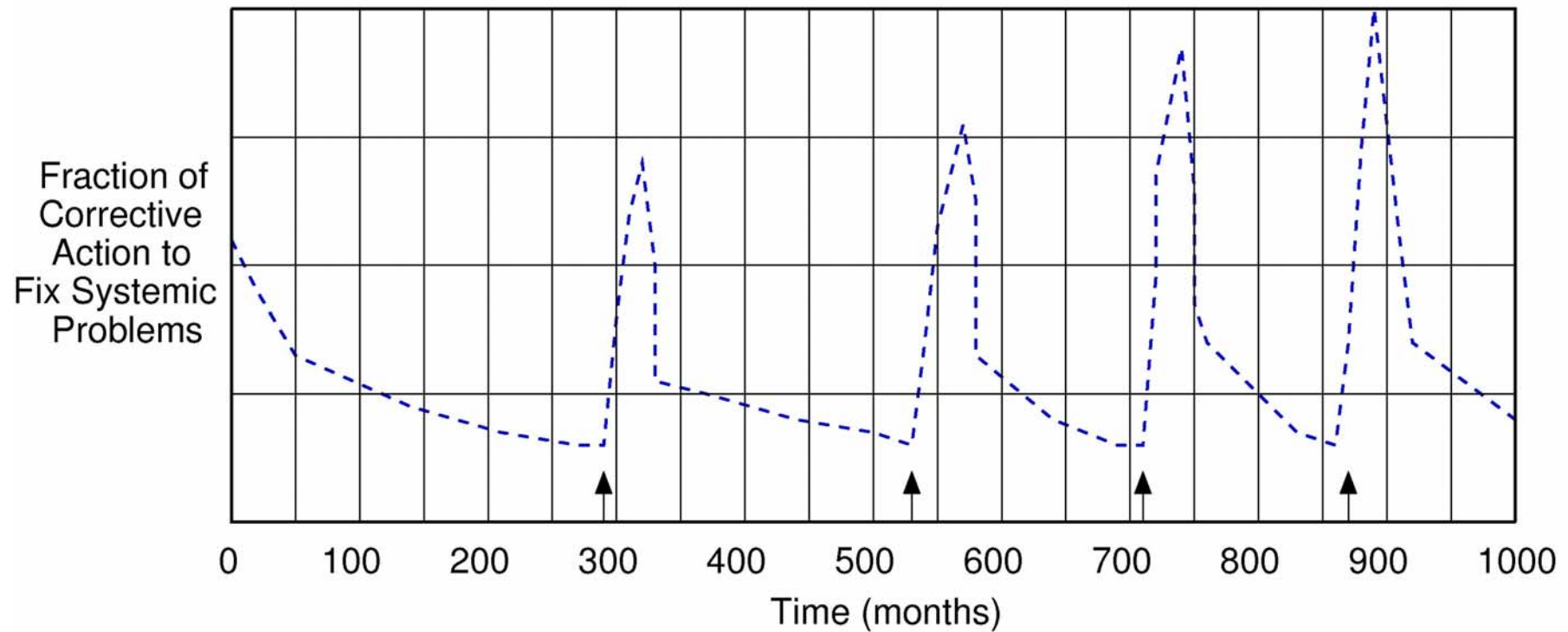
How can this model help us?

- It allows us to
 - Understand how and why accidents have occurred
 - Test and validate changes and new policies
 - Learn which “levers” have a significant and sustainable effect
 - Facilitate the identification and tracking of metrics to detect increasing risk

Accidents lead to a re-evaluation of NASA safety and performance priorities but only for a short time:

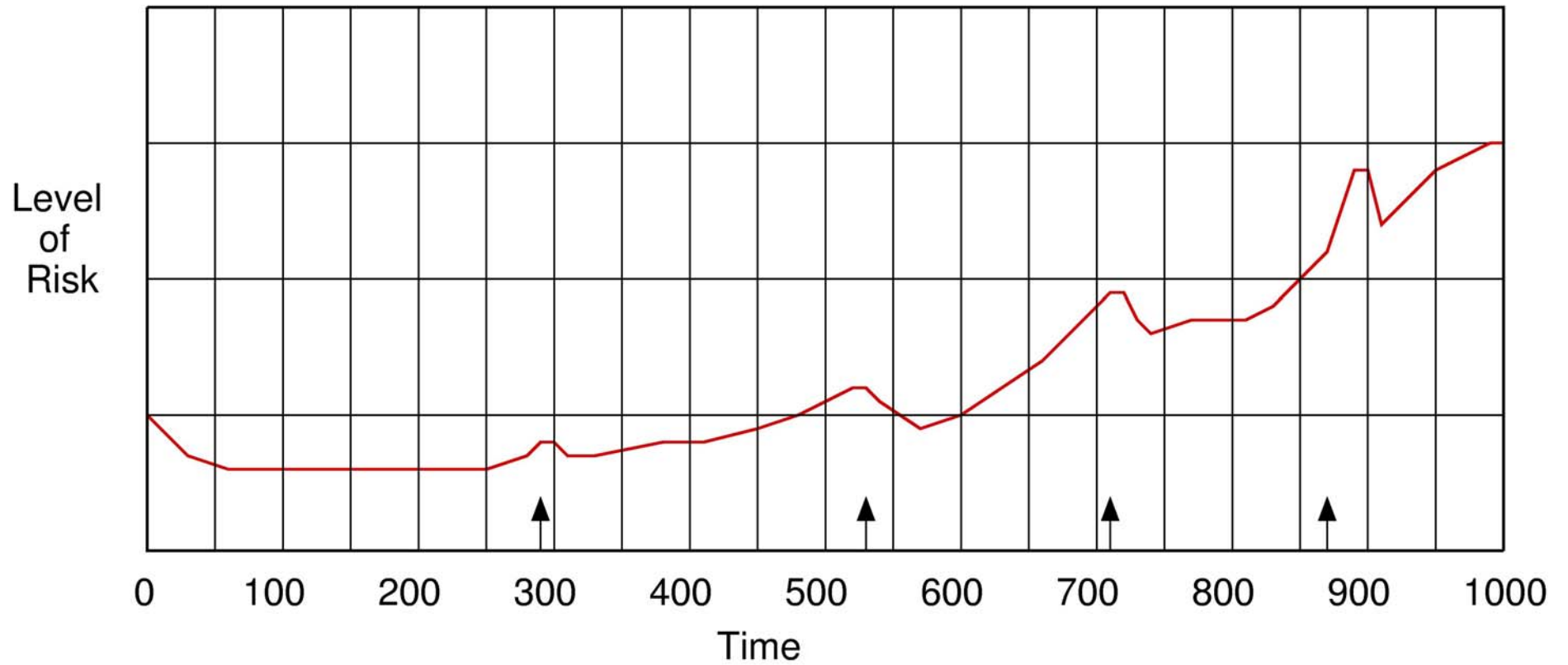


Attention to fixing systemic problems lasts only a short time after an accident

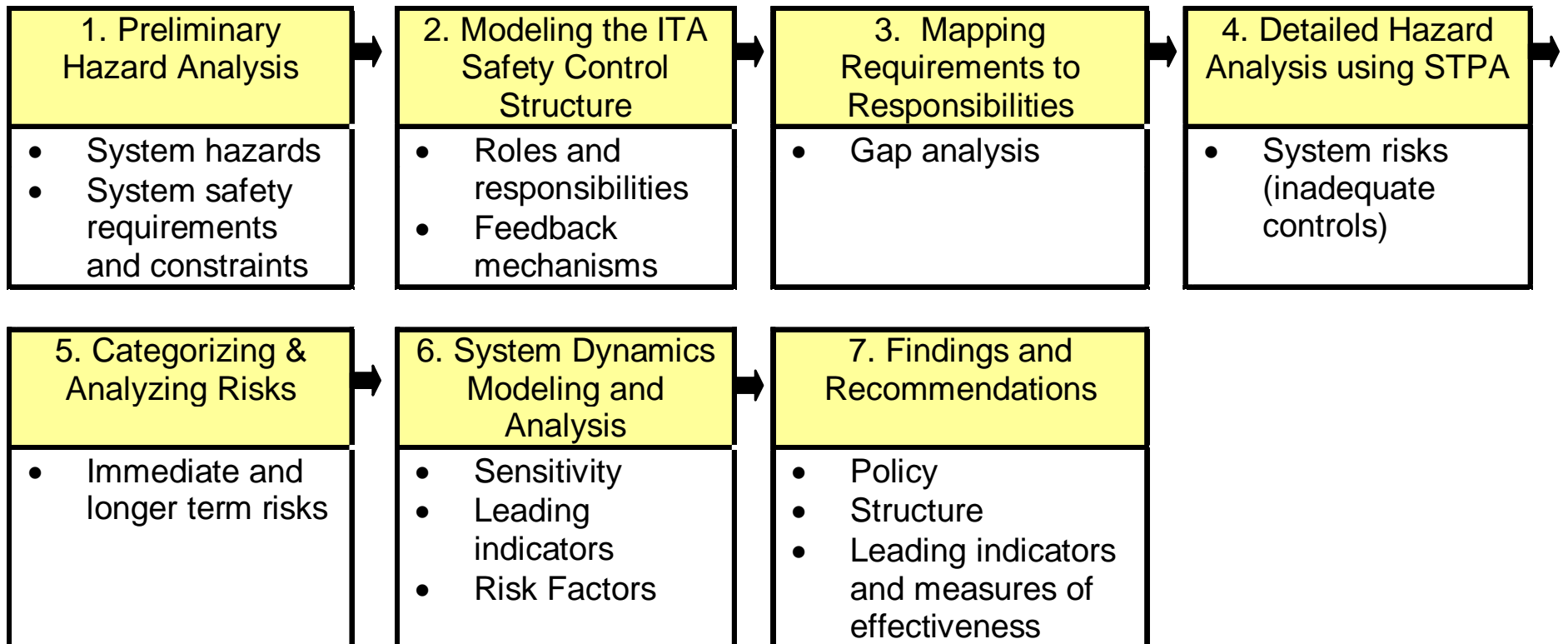


Attempts to fix systemic problems - - - - -

Responses to accidents have little lasting impact on risk



The Process

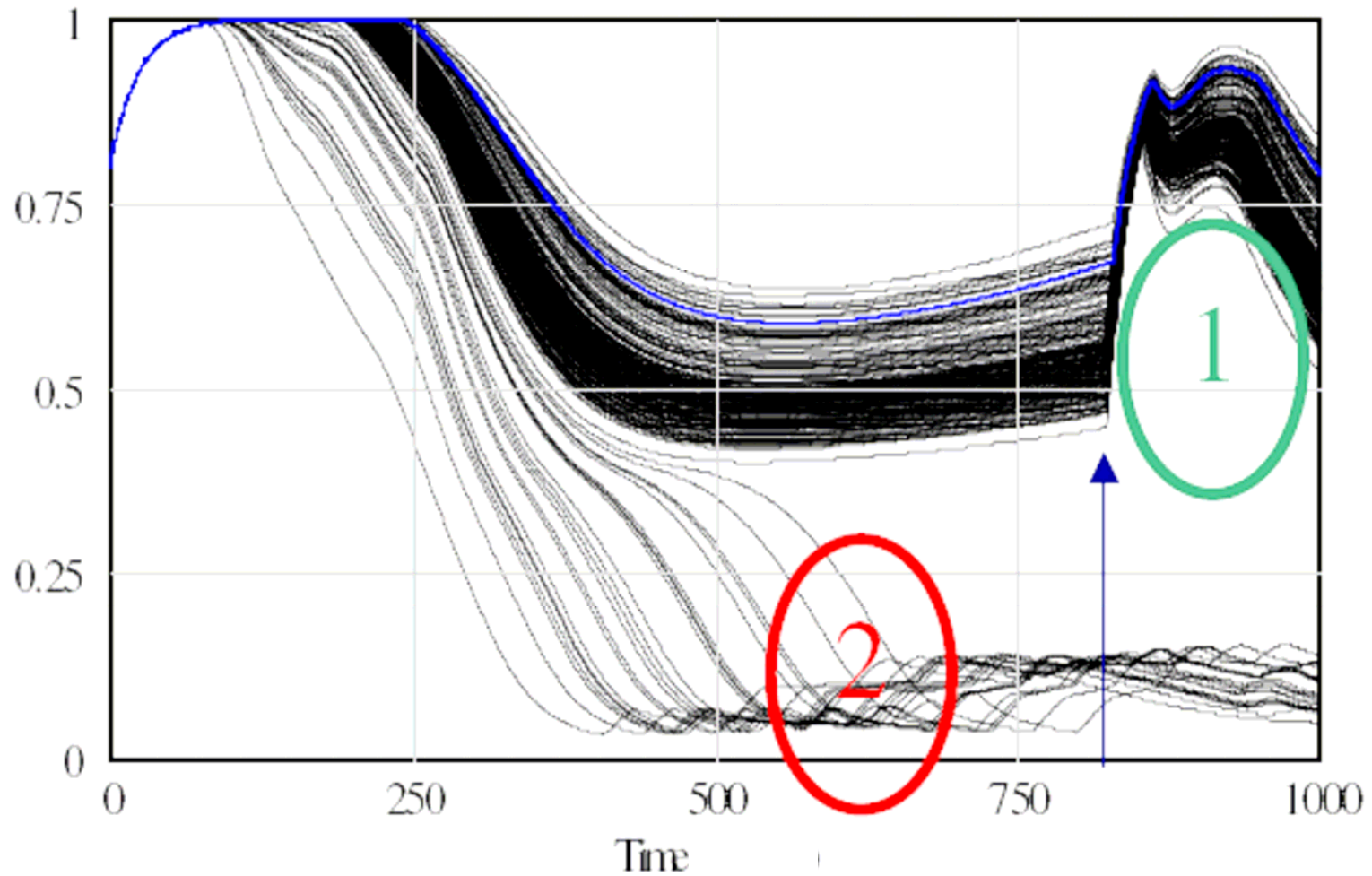


Example Result

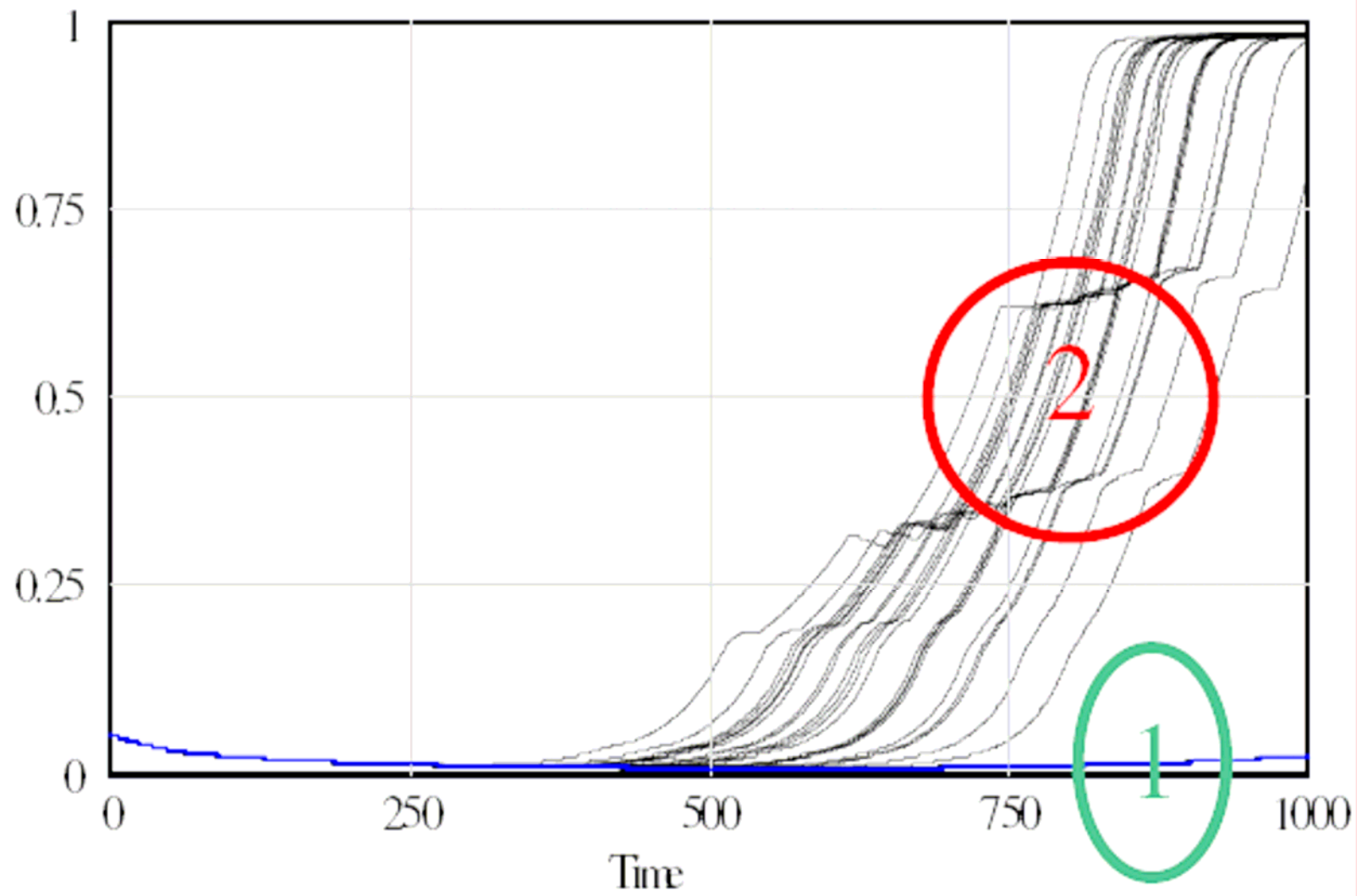
- ITA has potential to significantly reduce risk and to sustain an acceptable risk level
- But also found significant risk of unsuccessful implementation of ITA that needs to be monitored
 - 200-run Monte-Carlo sensitivity analysis
 - Random variations of +/- 30% of baseline exogenous parameter values

Sensitivity Analysis Results

Indicator of Effectiveness and Credibility of ITA



System Technical Risk



Successful Scenarios

- Self-sustaining for short period of time if conditions in place for early acceptance.
- Provides foundation for a solid, sustainable ITA program implementation under right conditions.
- Successful scenarios:
 - After period of high success, effectiveness slowly declines
 - Complacency
 - Safety seen as solved problem
 - Resources allocated to more urgent matters
 - But risk still at acceptable levels and extended period of nearly steady-state equilibrium with risk at low levels

Unsuccessful Implementation Scenarios

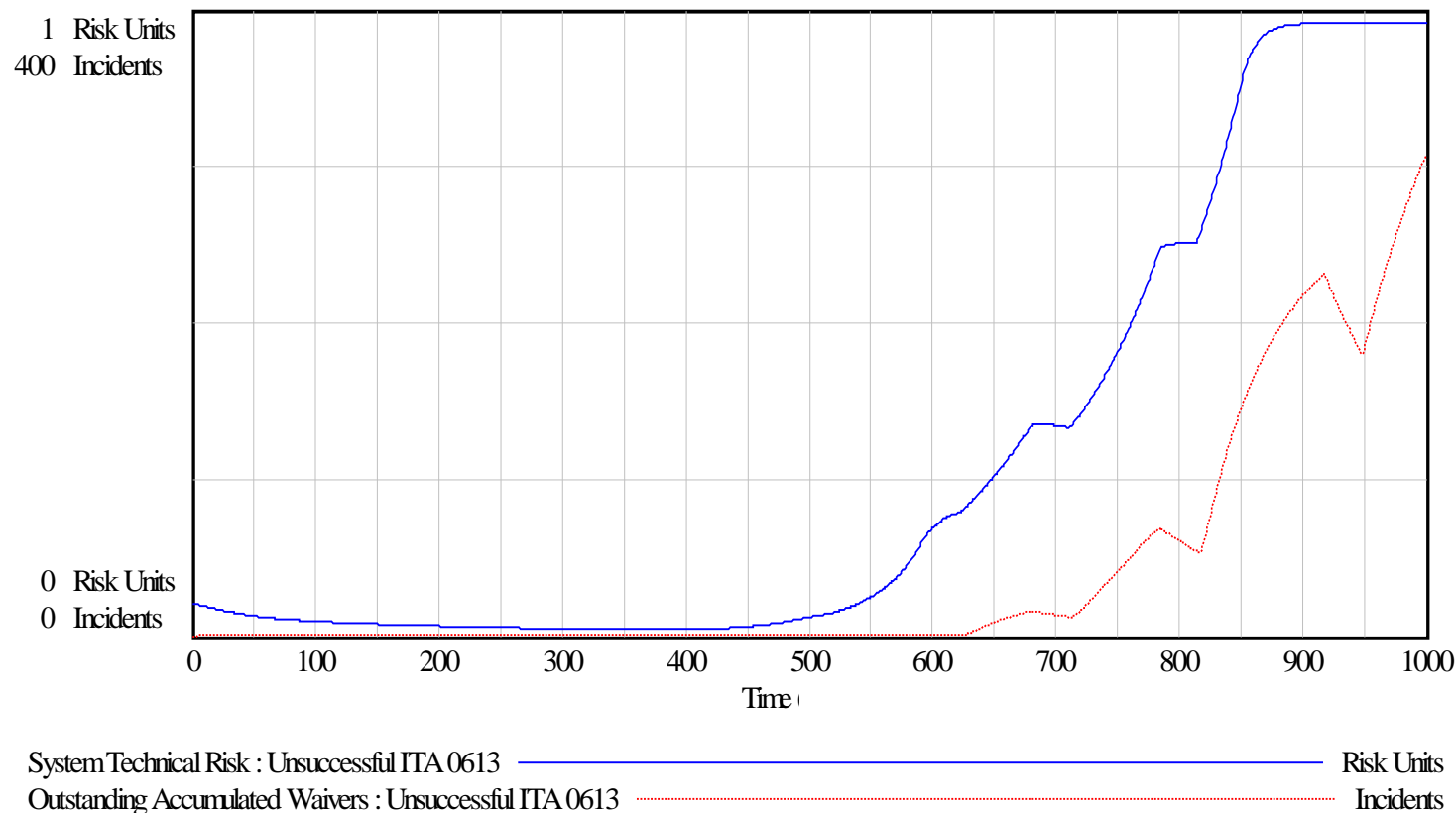
- Effectiveness quickly starts to decline and reaches unacceptable levels
 - Limited ability of ITA to have sustained effect on system
 - Hazardous events start to occur, safety increasingly perceived as urgent problem
 - More resources allocated to safety but TA and TWHs have lost so much credibility they cannot effectively contribute to risk mitigation anymore.
 - Risk increases dramatically
 - ITA and safety staff overwhelmed with safety problems
 - Start to approve an increasing number of waivers so can continue to fly.

Unsuccessful Scenario Factors

- As effectiveness of ITA decreases, number of problems increase
 - Investigation requirements increase
 - Corners may be cut to compensate
 - Results in lower-quality investigation resolutions and corrective actions
 - TWHs and Trusted Agents become saturated and cannot attend to each investigation in timely manner
 - Bottleneck created by requiring TWHs to authorize all safety-related decisions, making things worse
- Want to detect this reinforcing loop while interventions still possible and not overly costly (resources, downtime)

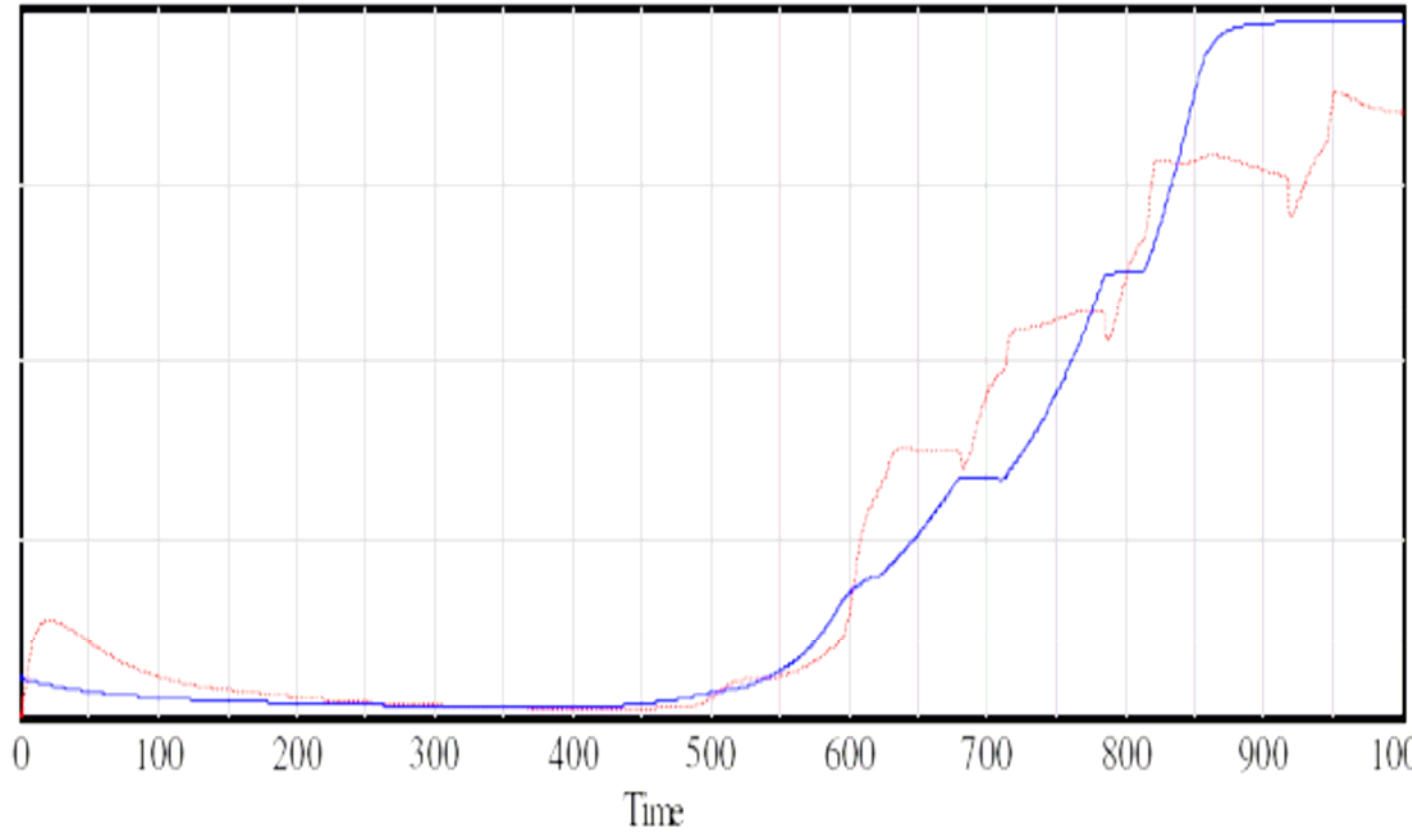
Lagging vs. Leading Indicators

- Number of waivers issued good indicator but lags rapid increase in risk



1 Risk Units
100 Incidents

0 Risk Units
0 Incidents



System Technical Risk : Unsuccessful ITA 0613 — Risk Units
Incidents Under Investigation : Unsuccessful ITA 0613 — Incidents